SETL Newsletter 192 6600, 370, and PUHA Microcode Nubbins

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May 13, 1977 R. Dewar A. Grand R. Kenner J. Schwartz

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This newsletter discusses compiled SETL code syle for the 6600 and the 370 and the microcode for the PUMA by defining the library linkages and general code style and giving rough timing estimates. The code is in assembler (or microcode in the case of the PUMA). Since access to different words and fields can be done quite differently at this level, to give symbolic names to offsets in the code would misleadingly imply that to change fields involves just a change in the definitions of the names. We will assume the SETL data structures as of the beginning of May and write the field names in the comments. 6600, 370, and PUHA Microcode Nubbins 6600 Nubbins

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This case is the simplest. The basic design considerations are as follows:

i) Not all nubbins are inline since some are too large.

ii) For offline nubbins at least a jump offline and a jump back are required and a certain amount of load-store work can be done in parallel with these jumps. (Actually, we will not be able to avoid a third jump.) iii) Since library calls can occur, only registers that are used in highly stereotyped ways in the LITTLE SRTL code can be used for other of the start and the start and the start and the start are used in the start and the start are used in the start are used in the start are used for other other and the start are used for other are used for other and the start are used for other and the start are used for other are used for are used for othe

The last consideration will be addressed first. We can use X0 to contain TVALMASK. This register is normally unused by the LITTLE compiler but the compiler can be modified to use that register when the appropriate mask is required. B1 will, as required by the LITTLE system, contain the constant one. B2 will contain the address of the heap. (Actually HEAP-1.)

The first two considerations suggest a 3-address style. The inputs of the operation will normally be loaded into X4 and X5 and the output will be placed into X6. This gives the following form for a call to an offline nubbin:

SA4	ARG1	Load first arg.
SA5	ARG2	Load second arg.
SA6	RESULT	Store previous result.
RJ	NUB	Call nubbin.

This occupies 2 words and takes about 2.3 microseconds.

If the result of the first operation is a "temporary" to be used immediately it need not be stored and reloaded; instead we can jump to a point at which an appropriate copy is performed. This leads to the "short form" call which is either:

SA4	ARG1	or	SA5	ARG2
RJ	NUB1		RJ	NUB2

This occupies one word and takes about 1.5 microseconds.

Since most of the time is spent in the RJ instruction, in a few favorable cases of short nubbins inline code may be generated.

A typical example of an offline nubbin is the following multiplication sequence:

MULT	BSS	1	Entry word.
+	BX1	-X0+X4	Get type, value for first arg.
	SX7	377777B	Get largest short integer.
	BX2	-10+15	Get type, value for second arg.

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IX3	X1- X7	See if arg. 1 too large.	,
IX 6	X1+X2	Do multiply.	/
IX2	X2-X7	See if arg. 2 too large.	
IX7	X6-X7	See if result is too large.	1
BX3	X3*X2	Now AND together the	,
BX3	X3 * X7	three test values.	
NG	X3,MULT	Done if all in range.	
SB3	=XLIBHULT	Else get library address.	(
RJ	LIBLINK	Branch to library.	
EQ	MULT	Return upon exit from library.	(

This takes about 4.7 microseconds.

The LIBLINK sequence which is used to link to the LITTLE-written library is as follows:

LIBLINK	BSS	1	Entry word.
	BX6	X 4	Copy first argument.
	SA 1	P1	Point to parm. list and first parm.
	BX7	X5	Copy second argument.
11. ↓	SA2	LIBLINK	Get entry word.
· · · · · ·	SA6	X1	Store first argument.
	SN7	X1+B1	Store second argument.
↓	BX6	X 2	Copy entry word.
	SA6	B3	Store at branch location.
•	JP	B3+1	Branch to library routine.
P1	CON	T1	First argument address.
	CON	T1+1	Second argument address.
T1	BSS	2	Space for the two arguments.

This takes about 3.7 microseconds to call the library.

Op-codes that merely call a library routine can have the following three-word inline "long form":

SA4	ARG1	Get first argument.
SA5	ARG2	Get second argument.
SA6	RESULT	Store previous result.
SB3	=Xentry	Get appropriate entry point.
RJ	LIBLINK	Go call library.

Thus, nubbins are not required for these cases, which are fairly numerous. Of course, two-word forms are available if X6 need not be stored.

The simplest SETL jumps are compiled as inline tests. Tests, such as the general equality test, which may involve library code, can have the following treatment:

S14	ARGI	Load first argument.
SA5	ARG2	Load second argument.

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1 A.	♦ 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	BX1	X4-X5	Get exclusive OR.	1
		SA6	RESULT	Store previous result.	3
		BX2	-10+11	Get value and type.	
. 1	↓ 1	ZR	X2, JUMPADR	Jump if equal.	6 3
. *		XX1	51	Get type alone for ARG1.	0
,	◆	SX3	7	T LATON + 1.	
		AX2	51	Get type alone for ARG2.	~D
		IX1	X1-X 3	Check type of first argument.	۲
• •	+	SB3	=XLIBEQUV	Get library address in case needed.	
		112	X2-X3	Check type of second argument.	æ.
		BX1	X1+X 2	Ensure both short.	0
	+	NG	X1,LAB	If so, not equal.	
• •		RJ	LIBLINK	Else, use library code.	
	+ 1	NZ	X6,JUMPADR	Jump if was equal.	9
•	LAB		-	• •	

This in-line code sequence is 7 words long and takes about 6.5 microseconds in the worst case in which the library is not called. Note that a word (and a few minor cycles) can be saved if X6 was an argument which did not have to be stored.

In-line addition is as follows:

SA4	ARGT	Load first argument.
SA5	ARG2	Load second argument.
SA6	RESULT	Store last result.
IX3	X4+X 5	Do addition.
BX6	-X0*X3	Leave just type and value.
BX7	1 6	Make copy to check type.
AX7	- 51	Leave just type.
ZR	X7,LAB	Branch if inline add.
SB3	=XLIBADD	Else call library routine
RJ	LIBLINK	to do the addition.

LAB

This is four words long and takes about 4.4 microseconds.

The inline subtraction nubbin is as follows:

SA4	ARG1	Load first argument.
SA5	ARG2	Load second argument.
BX1	X4+X5	Prepare to check both types.
IX2	X4-X5	Do subtraction.
S16	RESULT	Store previous result.
BX1	X1+X 2	See if result of subtract is negative.
BX6	-x0*x2	Get result type and value.
BX1	-10+11	Get check type and value.
XX1	51	Now get just check type.
SB3	= IL IBSUB	Get library entry point.
ZR	X1,LAB	If OK, skip library call.
RJ	LIBLINK	Else, call library.

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This occupies 5 words and takes about 5.1 microseconds.

As a final example, we consider the case of remote map retrieval by a quantity known to be a pointer to the relevant base. This can be done in an inline sequence as follows:

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+	SA5	ARG2	Load second argument.	
•	SA4	ARG1	Load first argument.	1
+	SB4	X5+B1	Prepare HEAP (VALUE (ARG2) +OFF_EBINDX) -	٢
	SAT	B4+B2	Load the above word.	
	. SB5	X4+2	Prepare to get HAXINDX.	
+	SA2	B5+B2 ⁻	Load maximum index word.	U)
	LX1	-18	Extract EBINDX field.	
	SA6	RESULT	Store last result.	A
+ .	HX3	-45	Get mask.	(9)
	BX3	-X3*X1	Get EBINDX (ARG2) .	
	LX2	-18	Position MAXINDX.	<i></i>
	SB3	X3+B1	Copy index to B-register.	U
+	SB2	X2+B1	Extract MAXINDX.	
	LE	B3,B2,SKIP	Skip next set if index in range.	
	SB3	B1	Else set index to zero.	9
SKIP	SB3	B3+B5	Prepare to load result.	
	SB3	B3+B2	Get HEAP address - 1.	
	SA1	B3+B1	Add tuple header length; load result.	
	BX6	X1	Get result.	

This occupies 7 words and takes about 6.5 microseconds. This, in fact, may be too long to do inline. If it were done offline, the code would be modified to put the SKIP label before the entry word. Note that 4-6 microseconds is a typical time for these important ? nubbins. Thus, code that never needs to enter the library should run at approximately 1/5 - 1/10 the speed of corresponding code generated by a reasonably good FORTRAN compiler.

⁶ 🔾 6600, 370, and PUHA Microcode Mubbins. 370 Nubbins. B. 370 Nubbins. ۲ The structure of these nubbins is different from those for the 6600 STREET'S !! for two major reasons: ٢ i) Jumps are a lot less expensive than on the 6600. ii) Registers are saved across library calls so a simple register allocator could be used. This leads to the following design: ۲ i) All nubbins are offline and entered with a BAL instruction. ii) Some registers will be reserved for scratch registers within the 'nubbins. iii) Other registers will be used to contain needed constants and base locators. iv) The rest of the available registers can be allocated by the 🕽 generated code to reduce the number of loads and stores. 9 The register usage is as follows: RO (11) First input to nubbin and return value. 8 R1 (A2) Second input to nubbin. Address mask (X*00FFFFFC*) R2 (AH) R3 (TVH) Type/value mask (X*FFFFFFFC*) R4 (HEAP) Base register pointing to HEAP-1. **R5** Base register for offline nubbins. **R6** Base registers for labels. **R7 (LBL)** Allocatable but used for jump address in tests. R8-R12 Allocatable. R13 (WA) Scratch for nubbins. О R14 Return address from nubbins. R15 (WB) Scratch for nubbins. A "worst case" call to a nubbin when everything must be loaded and ⁹ stored would be as follows: 0 Store last result. A1, RESULT ST L Load first argument. A1, ARG1 L A2, ARG2 Load second argument. 0 BAL R14,NUB Call the nubbin.

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This occupies 16 bytes. (Note that we will not attempt to give timings because of the large number of models and submodels.)

In a better (and more typical) case where items are in registers, the 🗿 code is as follows:

LR	12,R11	Second arg. (first was output)
BAL	R14, NUB	Go call nubbin.

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Thus requires only 6 bytes. Note that, unlike in the 6600 case, both BAL's are to the same location.

To call a library routine, a nubbin sets R15 to the entry point of the routine and branches to LIBLINK which is shown below.

LIBLINK	STH	11,12, ARGS	Store arguments.	
	LA	R13, SAVEAREA	Point to save area.	
	LA	R1,PLIST	Point to parameter list.	
•	BR	R15	Call routine; it returns inline.	<u></u>
PLIST	DC	A (ARGS, ARGS+4)	Parameter list.	ي ا
ARGS	DS	2F	Space for arguments.	
SAVEARBA	DS	18 P	Standard OS save area.	े

We will now present the 370 code for the nubbins shown in the 6600 section. 0

First, multiplication:

HULT	MR	11,11	Do the multiply.	3
	LTR	<u>λ1,λ1</u>	See if too large or not integer	S.
	BNZ	LHULT	Go offline if so.	
• •	SLDL	11,30	Else position result.	9
• • • •	NR	A1,TVH	Mask out junk bits.	
• •	CLR	λ1, λΗ	See if too large.	
	BNHR	R14	Return if not.	
LHULT	L	R15,=A (LIBMULT)	Else get library address.	
	В	LIBLINK	Now call library.	

For the branch cases, the inline code must load the address of the "true" label into register LBL and then call the nubbin. We will show the case of the equality test nubbin below.

EQUV	NR	A1,TVH	Remove junk from	
	WR	A2,TVH	both inputs.	9
	CLR	λ1,λ2	Compare both inputs.	
	BER	LBL	Branch if equal.	<i>_</i>
	SRL	A1,24	Now get type codes	9
	SRL	A2,24	for both inputs.	
	LA	WA,6	T_LATON.	~
,	CR	A1,WA	If greater, go offline.	0
	BH	LEQUV	Go call library.	
	CR	12,WA	If other type is OK, not equal.	
•	BNHR	R14	So return FALSE.	9
LEQUV	STR	A1, A2, ARGS	Else save arguments.	
	LA	R1, PLIST	Point to parameter list.	
	LA	R13, SAVEAREA	Point to save area.	
5 · · · •	ST	R14,RET	Save return address.	
• 2	L	$R15, =\lambda$ (LIBEQUV)	Get library routine address.	
• • • •	BALR	R14,R15	Call library.	9
•	LTR	RO,RO	Test return value.	
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		BNZR	TRI	Daturn if areal	
			LBL Dia Dem	Return if equal. Else load old return address.	0
. •		L	R14,RET		-
-	52 8	BR	R14	Return FALSE.	-
	RET	DS	1 P	Save location for return address	⁵ •)
	Wext, ad	dition:		•	
	100	3 10	11.10	na addition	0
•.	ADD	AR	A1,A2	Do addition.	-
		NR	A1,TVH	Remove junk bits.	
		CLR	A1, AB	See if type still OK.	
		BNHR	R14	Return if OK.	+
		L	R15,=A (LIBADD)	Else get library routine.	
		B	LIBLINK	Go call library.	0
	Next, su	btractic	on. This is similar	to addition except that the type	25
C" •			d before the actual		•
ъ,	SUB	NR	A1,TVH	Remove junk bits	
*.	300	NR	AZ,TVH	from both inputs.	
(CLR	•	see if in range.	0
ų, ² 4-4, .		BH	λ1,λΗ τςπρ		
·F1	n an	CLR		Go offline if not.	
Ċ			12,1M	Check second input.	0
1 ,***-		BH	LSUB	Branch if not in range.	-
		SR	λ1,λ2 D10	Now subtract.	
Č.	1.000	BNMR		Return if not negative.	
~	LSUB	L	R5,=A (LIBSUB)	Get library address.	
		В	LIBLINK	Go call library.	
(•		ote map retrieval below.	
()	OFRSH	WR	12,1H	Get offset from start of heap.	0
	ана. Ал	LH	WA, 16 (A2, HEAP)	Load EBINDX.	100
₹° • • •		LR	12,11	Get first arg. addressable.	
(÷	WR	A2,AM	Get value only.	0
	1	CH	WA, 12 (A2, HEAP)	Compare with MAXINDX.	~
		BNH	SKIP	Index in range.	
Č	CETD	SR	WA,WA	Else set index to zero.	Э
.	SKIP	SLL AR	WA,2	Get correct offset.	-
••••• •		L	A2,WA A1 16/32 HPADA	Get HEAP offset - 4.	
$C_{\rm eff}$ is	· .	BR	A 1, 16 (A2, HEAP) R 14	Load result value. Now return.	
-		DK	д 14 .	now return.	
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This case is entirely different because we are dealing with a microprogamable machine. Grossly described, what we intend to do is to emulate both the "normal" 6600 instructions (and maybe add a few for efficiency) and special SETL instructions and have the microcode handle the state switching.

These SETL instructions will correspond to calls to nubbins in the $^{\bigcirc}$ above two cases. If the nubbins do not require a call to the library, they can be done by the microcode in a manner similar to the way the microcode would execute a 6600 instruction. If the nubbin required a library call, a microcode source would library call, a microcode sequence would be entered to call the library. The library would execute a special instruction to return to the SETL mode and set the result.

The PUMA has, in addition to the X, A, and B registers, 8 60-bit Y registers. These registers are used in the normal 6600 emulation as scratch registers but if we could restrict their usage as scratch registers, they could be used as registers in the "SETL machine" mode. In fact, the only place where more than one or two of the Y registers are currently used is in the multiply routine. If we were to accept a multiply which is 3 times slower, we could have the rest of the Y registers free for the SETL instructions and they would persist over the LITTLE-written library.

In addition, we need a register to hold, in 6600 mode, the return point to SETL mode. We can use Y1 for this register. That means that Y0 can be used as the scratch register in 6600 mode and those few places where a second scratch register is needed can be re-written to use only one. That leaves Y2-Y7 as registers for the SETL instructions which will persist over the library calls. We can use the X registers as scratch in SETL mode so that YO and Y1 can be used for data that need not persist over library calls. 0

The SETL instructions will have a format similar to the normal 6600 instructions. The op-code and I fields of the 6600 instruction will be used for the SETL op-code and the J and K fields will be used as usual. Bit 1 of the op-code will be the library flag. If it is on, it means that this operation is merely a call to the library and no processing can Э be done by microcode. This means that the microcode can simply call the library directly without having to have special code for that operation. The low-order bit of the op-code is used for operation sub-types. For binary operations which return an output this bit is used to indicate which register receives the output. If it is on, Y7 receives the output; otherwise, Y6. In other cases, it is used to differentiate such things as branch TRUE/FLASE, load/store, and give two related op-codes when there is no need for three registers. Note that branches, loads, and stores will use the load for the stores. stores will use the long form of the instructions which is the same as for 6600 instructions.

We will have the global register usage over both 6600 and SETL modes) the same as for the 6600 nubbins above. Wamely, X0 will hold TVALMASK, B1 will hold the constant 1, and B2 will contain the address of HEAP(0).

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There will be a table of entry points to the library at memory locations known to the microcode. At each entry point will be a special program-stop instruction which will return control to SETL mode in a case where the library routine would normally return. This instruction can be placed at the entry word by an initialization routine. Note that it is assumed that the called routine does not do funny things with its entry word other that branch to it to return. This is the case in LITTLE-written code and COMPASS routines are not supposed to do things with this word in any event.

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When the microcode wants to call the library, it places into E1 the main storage address of the entry point to which it desires to branch and jumps to micro-instruction LIBLINK which is is shown below. It builds, in Y1, a value containing the parcel count into the current instruction word, the address of the current word (which is P+1 by this time), and the value to which it will branch. The latter is used for safety as follows. When a "return to SETL" instruction is encountered, it must only occur at one minus the last jump point taken to the library. Thus, the P value at that time must agree with the branch address stored in Y1. LIBLINK will also save the two input arguments into a parameter list and set A1 and X1 according to the normal calling conventions (A1 contains the address of the parameter list and X1 contains the address of the first parameter).

LIBLINK P=P-1: BO=E1: IP -NIWEMPTY THE LLONWRD An instruction fetch is in progress. Wait it out. LLNWAIT NIW=CHRD; IF -CHDONE THEN LLNWAIT * Read to next inst. word. LLONWRD CLEAR; AC=E0; E0=PLISTaddr; IF CHDONE THEN LLONWRD HA=AC; READ; AC=E0; E0=T1addr; * Read up branch address. A1=AC; AC=E0 * Set parm. list address; set store address. X1=AC; AC:MQ=SHIFT (P:MQ, R16) * Start shifting P value. MQ=SHIPT (AC:MQ, R16) * Continue shift. MQ=AC; AC=MQ; E2=7; NEWPARCEL * Shift; start parcel counting. X2=AC: E2=E2+1[P]: NEWPARCEL: IF ~LASTPARCEL THEN LLNPLP LLNPLP LLREAD AC=CHRD: BUT=YJ: IF -CHDONE THEN LLREAD * Wait for data. CLEAR; P=AC; AC=E0; E0=E1; IF CHDONE THEN LLWT1 LLWT1 MA=AC; AC=BUF; WRITE; P=P+1 * Start parm. write; set branch adr. ಾ LLWT2 BUF=X2; IF -CHDONE THEN LLWT2 * Wait for store accept. CLEAR; AC=P * Reset memory; get branch address. AC=AC|BUP; BUP=YK * Insert branch location; get parm. 2 3 Y1=E2:AC; E0=T2addr * Set save word; get parm. 2 store addr. AC=BO; IF CHDONE THEN LLWT3 * Wait for memory. LLWT3 HA=AC; AC=BUF; WRITE * Start write of second parm. ٦ LLWT4 IF -CHDONE THEN LLWT4 * Wait for accept. CLEAR; GO LBRANCH * Reset memory; enter LITTLE mode.

This takes about 1.31 microseconds. We will assume in timing) estimates for the PUMA that a cycle is 45ns and memory cycle is 470ns.

We will now present the new microcode for the program stop instruction which will process the special "return to SETL" instruction. We will manga to the 6600, 370, and PUHA Microcode Nubbins. PUHA Microcode Nubbins.

> assume that we are using an I field of one to indicate this instruction and that, for clarity, no other sub-types of program stop exist.

E0=2000; IF -I(0) THEN ERROR * Process normal PS. **L00** E1:BUF=Y1: AC=P: IF I(1) THEN ERROR * Get return word. (AC) = AC-BUP[18]; IF I(2) THEN ERROR * Start address check. AC=AC-BUP[18]; IF -NIWEMPTY THEN LOOSK * Continue test. IP -CHDONE THEN LOOWT1 * Wait out instruction fetch. LOOWT1 NIW=CMRD; CLEAR * Clear out instruction fetch. LOOSK IF -AC=0 THEN ERROR * Finish validity check. ر. الا ب AC=SHIFT (BUF:MQ, R16); BUF=X6; E0=2; CIW=NIW AC=SHIPT (AC:MQ,R4): BO=E0-1[F]; IF EALU (0) SEALU (1) THEN LOOSLP LOOSLP LOOWT2 P=AC: IP CHDONE THEN LOOWT2 * Wait for free memory. 3 LOOWT3 MA=P; READ; NIW=CMRD; IF -CHDONE THEN LOOWT3 CIW=NIW; AC=BUF; CLEAR; P=P+1; LATCH I * Get to return word. =3-E1: NA=P: READ; IF EALU THEN RETOUT * RNI; test pos. 3 LOOPLP NEWPARCEL: LATCH I: B1=E1+1[F] * Get to correct position. =3-E1; IF EALUP THEN RETOUT ELSE LOOPLP * See if done.

This takes about 1.35 microseconds.

Next we will present the microcode which handles the return from a binary operation with a result to give an idea of the type of \Im Ger war i housekeeping needed.

RETOUT NEWPARCEL: LATCH I: IF I (0) THEN ROUT7 ROUT6 Y6=AC: IF ICHECK THEN SICHECK ELSE SOPCODEBRANCH ROUT7 **Y7=AC: IF ICHECK THEN SICHECK ELSE SOPCODEBRANCH**

This takes 90ns and will be included in the timings of the nubbins which jump to it (although the other overhead operations will not be included).

Next we present the microcode for some of the simpler operations. First, addition and subtraction:

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BUF=YJ * Get first input. AC=BUF; BUF=YK * Copy first; get second input. * Start addition. (AC) =AC+BUP AC=AC+BUF; BUF=X0; E1=LIBADD * Finish add; get mask AC=AC6-BUF; E0:X6=AC * Do mask and set to check type. =370+E0; IF EALUP THEN RETOUT ELSE LIBLINK * Complete.

SUB

BUP=YJ * Get first input. AC=BUF; BUF=YK * Copy first; get second input. (AC) = AC-BUP; E0:X6=AC * Start subtract; get check type. AC=HQ; HQ=AC-BUP; =370+E0; IF ¬EALUP THEN LIBLINK AC=BUF; BUF=X0 * Get second input; get TVALMASK. E0:X6=AC; AC=MQ * Check second type; get subtract result. AC=AC6-BUF; =370+E0; IF -EALUP THEN LIBLINK * Mask; check. 11 🕥

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E0:X6=AC * Get check type for output. =370+E0: IF EALUP THEN RETOUT ELSE LIBLINK * Done.

-⁵⁰ O .36 microseconds and subtraction takes Addition takes microseconds.

Next, we present the case of remote map retreival shown above. It will be very helpful in understanding the microcode below to refer to the $^{\bigcirc}$ COMPASS code for the same routine above.

BUF=YK; AC=HQ; HQ=0 * Get second input; clear MQ. SOFRSM AC=BUF; BUF=B2; E0=2; IF -NIWEMPTY THEN SOFRWT1 SOFRWTO NIW=CHRD; IF -CHDONE THEN SOPRWTO * Wait for fetch. SOFRWT1 CLEAR; (AC) = AC+BUF[18][NOP]; IF CHDONE THEN SOFRWT1 AC=AC+BUP[18][NOP]; BUPYJ * Get addr. EBINDX; get first arg. MA=AC: READ: AC=E0 * Read BBINDX word: set AC to 2. (AC) = AC+BUP[18] * Prepare to get HEAP offset of MAXINDX. AC=AC+BUP[18]; BUP=B2 * Finish add; get HEAP address. SOFRWS2 (AC) = AC+BUF[18]; IF -CHDONE THEN SOFRWT2 * Wait for read. AC=AC+BUF[18] * Get address for MAXINDX. SOPRWT3 CLEAR; MA=AC; X6=AC; IF CHDONE THEN SOPRWT3 * Wait for mem. AC=CMRD; READ * Get EBINDX word; start read of MAXINDX. X5=AC; AC:MQ=SHIFT(-1:MQ,R16) * Save word; build mask. AC:MQ=SHIPT(AC:MQ,L1); BUF=X5 * Cont. with mask; get word. at see a X5=AC; AC=SHIFT (BUF:MQ,R16) * Save mask; shift data. AC=SHIPT (AC:HQ,R1); BUP=X5 * Cont. shift; get mask. AC=SHIPT (AC:HQ,R1) * Pinish shift. * Extract EBINDX. AC=AC6BUP SOPRWT4 X5=AC; IF -CHDONE THEN SOPRWT4 * Save EBINDX; wait MAXINDX. AC=SHIPT (CHRD: NO, R16); CLEAR * Position MAXINDX. AC=SHIFT(AC:MQ,R1)* Continue shift. AC=SHIPT (AC:MQ,R1) * Finish shift. (AC) = AC + 0[18]* Mask out MAXINDX. AC=AC+0[18]; BUF=X5 * Complete: get EBINDX (AC) = AC-BUF[18] * Start range test. • (AC) = AC-BUF[18]; IF -EALU (59) THEN SOFRSKP * In range. BUP=BO * Else use index of zero. SOFRSKP AC=BUF; BUF=X6 * Get index and address. (AC) = AC + BUP[18][NOP]* Get address to load from. AC=AC+BUF[18][NOP]; BUF=B2 * Finish add; get HEAP address. SOPRWT5 (AC) = AC+BUP[18][NOP]; IF CHOONE THEN SOPRWT5 * Get address to load. AC=AC+BUP[18][NOP]* Read result value. MA=AC; READ SOFRWIG IF -CHDONE THEN SOFRWIG * Wait for read to complete. AC=CMRD; CLEAR; NEWPARCEL; LATCH I; IF I(0) THEN ROUT7 ELSE ROUT6

This takes about 2.61 microseconds.

Por tests of one input that input is given in the J field of the branch instruction. For tests of two inputs, a "compare" instruction is used and a "condition code" is saved in the output register. Then, a

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"branch on condition" is used to branch TRUE or FALSE depending on the "condition code" stored in its input register. As an example of the two-input test, we present the equality test which was shown earlier in 6600 and 370 assembly code.

EQUVBUF=YJ* Get first input.AC=BUF; BUF=YK* Copy first input; get second input.AC=AC/BUF; BUF=X0* Do exclusive OR; get TVALMASK.AC=ACC-BUF; B0:BUF=YK; E2=1* Mask; get type; get TRUE.=67-E0; E1:BUF=YK; IF AC=0 THEN TRUE* Check; get type; true=67-E0; IF EALU(11) THEN LIBLINK* This is long type.=67-E1; BUF=B0* Start other test; get FALSE.=67-E1; AC=BUF; IF EALU(11) THEN LIBLINK ELSE RETOUTTRUEAC=E2; NEWPARCEL; LATCH I; IF I(0) THEN ROUT7 ELSE ROUT6

This takes about .40 micoseconds.

Therefore, we see that the simpler nubbins which do not do memory accesses are about 10-11 times faster than those running on the 6600 and those whicp access memory or involve library linkages are about 3 times faster.

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